

CLAIMS

What is claimed is:

- 1 1. An apparatus for calibrating a machine measuring system that has a first
2 measuring device and a second measuring device, the apparatus comprising:
3 a first calibration target mounted in a predetermined relationship to the first
4 measuring device of the machine measuring system;
5 a third measuring device mounted in a predetermined relationship to the second
6 measuring device of the machine measuring system; and
7 a data processor configured to calculate a relative measuring-device position value
8 of the machine measuring system based on a relative position of the first
9 calibration target to the third measuring device; wherein the relative
10 measuring-device position value of the machine measuring system
11 represents the position of the first measuring device relative to the second
12 measuring device.
- 1 2. An apparatus as recited in Claim 1, wherein each measuring device is selected
2 from a group consisting of:
3 an image-capturing device configured to capture images for use in
4 calculating the relative measuring-device position value of the
5 machine measuring system;
6 a gravity gauge configured to detect movement of one or more other
7 measuring devices with respect to another measuring device or
8 with respect to a fixed point;
9 a string gauge configured to detect movement of one or more other
10 measuring devices with respect to another measuring device or
11 with respect to a fixed point; and
12 a light source located near one measuring device to direct a light beam at a
13 detector that is located near another measuring device.

1 3. An apparatus as recited in Claim 1, wherein, in operation:
2 a value that represents the position of the first calibration target relative to
3 the third measuring device is stored as a calibration value;
4 the third measuring device is configured to periodically measure a new
5 value that represents a new position of the first calibration target
6 relative to the third measuring device; and
7 if the calibration value differs from the new value beyond an acceptable
8 amount, then an alert alarm is raised.

1 4. An apparatus as recited in Claim 3:
2 wherein, in operation, the difference in the calibration value and the new
3 value is used in updating the relative measuring-device position
4 value of the machine measuring system.

1 5. An apparatus as recited in Claim 3:
2 wherein, in operation, upon recognizing that the calibration value differs
3 from the new value beyond an acceptable amount, the relative
4 measuring-device position value of the machine measuring system
5 is recalculated.

1 6. An apparatus as recited in Claim 1, wherein, in operation:
2 a value that represents the position of the first calibration target relative to
3 the third measuring device is stored as a calibration value;
4 a new value that represents the position of the first calibration target
5 relative to the third measuring device is periodically measured; and
6 if the calibration value differs from the new value beyond an acceptable
7 amount, then an alert alarm is raised.

1 7. An apparatus as recited in Claim 1, wherein the data processor is further
2 configured to compute the relative measuring-device position value of the
3 machine measuring system based on:

4 measuring device of the machine measuring system are measuring targets of
5 objects under measurement.

1 12. An apparatus as recited in Claim 1, wherein the data processor is further
2 configured to:

3 compute a modified relative measuring-device position value of the
4 machine measuring system while the first measuring device and the
5 second measuring device of the machine measuring system are
6 measuring targets of objects under measurement, and
7 modify measurements produced by measuring the targets of objects under
8 measurement based on the modified relative measuring-device
9 position value of the machine measuring system.

1 13. An apparatus as recited in Claim 12, wherein the data processor is further
2 configured to modify measurements produced by measuring the targets of objects
3 under measurement based on the modified relative measuring-device position
4 value of the machine measuring system only when the modified relative
5 measuring-device position value differs from the relative measuring-device
6 position value by more than a predetermined value.

1 14. An apparatus as recited in Claim 1, wherein the machine measuring system is one
2 in which each of the first measuring device, the second measuring device, and the
3 third measuring device is an image-capturing device that performs measurements
4 of objects by capturing images.

1 15. An apparatus as recited in Claim 1, wherein the machine measuring system is one
2 in which any one of the first measuring device, the second measuring device, and
3 the third measuring device is an image-capturing device that performs
4 measurements of objects by capturing images.

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5 wherein the means for measuring a position of a first device of the plurality of
6 devices relative to a second device of the plurality of devices includes:
7 a calibration device mounted near the first device in which the
8 position of the calibration device relative to the first device
9 is predetermined;
10 a calibration target mounted near the second device in which the
11 position of the calibration target relative to the second
12 device is predetermined;
13 means for measuring the position of the calibration device relative
14 to the calibration target; and
15 means for measuring the position of the first device relative to the
16 second device based on:
17 (1) the position of the calibration device relative to
18 the first device;
19 (2) the position of the calibration target relative to
20 the second device; and
21 (3) the position of the calibration device relative to
22 the calibration target.

1 20. An apparatus as recited in Claims 19 wherein the calibration device constitutes the
2 means for measuring the position of the calibration device relative to the
3 calibration target.

1 21. A method for calibrating a machine measuring system that has a first measuring
2 device and a second measuring device, the method comprising the steps of:
3 mounting a first calibration target in a predetermined relationship to the
4 first measuring device of the machine measuring system;
5 mounting a third measuring device in a predetermined relationship to the
6 second measuring device of the machine measuring system; and

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7 calculating a relative measuring-device position value of the machine
8 measuring system representing the position of the first measuring
9 device relative to the second measuring device based on a position
10 of the first calibration target relative to the third measuring device.

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1 22. A method as recited in Claim 21, including selecting each measuring device from
2 a group consisting of
3 an image-capturing device configured to capture images for use in
4 calculating the relative measuring-device position value of the
5 machine measuring system;
6 + a gravity gauge configured to detect movement of one or more other
7 measuring devices with respect to another measuring device or
8 with respect to a fix point;
9 + a string gauge configured to detect movement of one or more other
10 measuring devices with respect to another measuring device or
11 with respect to a fix point;
12 a light source located near one measuring device to direct a light beam at a
13 detector that is located near another measuring device.

1 23. A method as recited in Claim 21, including storing a value that represents the
2 position of the first calibration target relative to the third ^{optical sensor} measuring device as a
3 calibration value; wherein
4 the third measuring device periodically measures a new value that
5 represents a new position of the first calibration target relative to
6 the third measuring device; and
7 if the calibration value differs from the new value beyond an acceptable
8 amount, then raising an alert alarm.

- 1 24. A method as recited in Claim 23, including applying the difference in the
2 calibration value and the new value to update the relative measuring-device
3 position value.
- 1 25. A method as recited in Claim 23 including, upon recognizing that the calibration
2 value differs from the new value beyond an acceptable amount, recalculating the
3 relative measuring-device position value.
- 1 26. A method as recited in Claim 21, including:
2 storing a value that represents the position of the first calibration target
3 relative to the third measuring device as a calibration value;
4 periodically measuring a new value that represents the position of the first
5 calibration target relative to the third measuring device; and
6 if the calibration value differs from the new value beyond an acceptable
7 amount, then raising an alert alarm.
- 1 27. A method as recited in Claim 21, further comprising the step of computing the
2 relative measuring-device position value of the machine measuring system based
3 on:
4 a first relative measuring-device position value that represents a position of
5 the second measuring device relative to the third measuring device,
6 and
7 a second relative measuring-device target position value that represents a
8 position of the first measuring device relative to the first calibration
9 target.
- 1 28. A method as recited in Claim 27, wherein the second relative measuring-device
2 target position value is computed based on a position of the first calibration target
3 relative to a second calibration target.

1 29. A method as recited in Claim 28, wherein the position of the first calibration
2 target relative to the second calibration target is obtained by using a fourth
3 measuring device which provides information to calculate the position of the first
4 calibration target relative to the second calibration target.

1 30. A method as recited in Claim 28 wherein:
2 the position of the first calibration target relative to the second calibration
3 target is obtained by using an image-capturing device;
4 images of the first calibration target and the second calibration target are
5 provided by placing the first calibration target and the second
6 calibration target in the view of the image-capturing device; and
7 the images of the first calibration target and the second calibration target
8 are applied to calculate the position of the first calibration target
9 relative to the second calibration target.

1 31. A method as recited in Claim 21, further comprising the step of computing the
2 relative measuring-device position value of the machine measuring system while
3 the first measuring device and the second measuring device of the machine
4 measuring system are measuring targets of objects under measurement.

1 32. A method as recited in Claim 21, further comprising the steps of:
2 computing a modified relative measuring-device position value of the
3 machine measuring system while the first measuring device and the
4 second measuring device of the machine measuring system are
5 measuring targets of objects under measurement, and
6 modifying measurements produced by measuring the targets of objects
7 under measurement based on the modified relative measuring-
8 device position value of the machine measuring system.

1 33. A method as recited in Claim 32, wherein the step of modifying measurements
2 produced by measuring the targets of objects under measurement based on the

3 modified relative measuring-device position value of the machine measuring
4 system is performed only when the modified relative measuring-device position
5 value differs from the relative measuring-device position value by more than a
6 predetermined value.

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1 34. A method as recited in Claim 21, wherein each of the first measuring device, the
2 second measuring device, and the third measuring device is an image-capturing
3 device that performs measurements of objects by capturing images.

1 35. A method as recited in Claim 21, wherein any of the first measuring device, the
2 second measuring device, and the third measuring device is an image-capturing
3 device that performs measurements of objects by capturing images.

1 36. A method for calibrating a machine measuring system that has a first measuring
2 device and a second measuring device, the method comprising the steps of:
3 mounting a calibration device in a fixed relationship to at least the first
4 measuring device for detecting change of position of the second
5 measuring device relative to the first measuring device; and
6 measuring the position of the first measuring device relative to the second
7 measuring device based on predetermined information specifying a
8 position of the first measuring device relative to the calibration
9 device, and based on information received from the calibration
10 device that indicates change of position of the second measuring
11 device relative to the first measuring device.

1 37. A method as recited in Claim 36, wherein the step of measuring comprises the
2 step of using a light source mounted in fixed relationship to the first measuring
3 device and a light detector mounted in fixed relationship to the second measuring
4 device to detect the change of position of the second measuring device relative to
5 the first measuring device.

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1 38. A method for measuring the relative positions of a plurality of devices, the method
2 comprising the steps of:
3 for a position of a first device of the plurality of devices relative to a
4 second device of the plurality of devices,
5 mounting near the first device a calibration device in which the
6 position of the calibration device relative to the first device
7 is predetermined;
8 mounting near the second device a calibration target in which the
9 position of the calibration target relative to the second
10 device is predetermined;
11 measuring the position of the calibration device relative to the
12 calibration target; and
13 determining the position of the first device relative to the second
14 device based on:
15 the position of the calibration device relative to the
16 first device;
17 the position of the calibration target relative to the
18 second device; and
19 the position of the calibration relative device to the
20 calibration target.

1 39. A computer-readable medium bearing instructions for calibrating a machine
2 measuring system that has a first measuring device and a second measuring device
3 adapted to be mounted in a predetermined spatial relationship to each other, a first
4 calibration target adapted to be mounted in a predetermined spatial relationship to
5 the first measuring device, and a third measuring device adapted to be mounted in
6 a predetermined spatial relationship to the second measuring device, the
7 computer-readable medium comprising instructions for performing the steps of:
8 calculating a relative measuring-device position value of the machine
9 measuring system based on a position of the first calibration target
10 relative to the third measuring device, the relative measuring-

11 device position value of the machine measuring system
12 representing the position of the first measuring device relative to
13 the second measuring device.

1 40. A computer-readable medium as recited in Claim 39, further comprising
2 instructions for performing the step of computing the relative measuring-device
3 position value of the machine measuring system while the first measuring device
4 and the second measuring device of the machine measuring system are measuring
5 targets of objects under measurement.

1 41. A computer-readable medium as recited in Claim 39, further comprising
2 instructions for performing the steps of:
3 computing a modified relative measuring-device position value of the
4 machine measuring system while the first measuring device and the
5 second measuring device of the machine measuring system are
6 measuring targets of objects under measurement, and
7 modifying measurements produced by measuring the targets of objects
8 under measurement based on the modified relative measuring-
9 device position value of the machine measuring system.

1 42. A computer-readable medium as recited in Claim 41, wherein the step of
2 modifying measurements produced by measuring the targets of objects under
3 measurement based on the modified relative measuring-device position value of
4 the machine measuring system is performed only when the modified relative
5 measuring-device position value differs from the relative measuring-device
6 position value by more than a predetermined value.

1 43. A computer-readable medium bearing instructions for calibrating a machine
2 measuring system that has a first measuring device and a second measuring device
3 adapted to be mounted in a predetermined spatial relationship to each other, and a

4 calibration device adapted to be mounted in a predetermined spatial relationship to
5 at least the first measuring device for detecting change of position of the second
6 measuring device relative to the first measuring device, the computer-readable
7 medium comprising instructions for performing the steps of:
8 measuring the position of the first measuring device relative to the second
9 measuring device based on predetermined information specifying a
10 position of the first measuring device relative to the calibration
11 device, and based on information received from the calibration
12 device that indicates change of position of the second measuring
13 device relative to the first measuring device.

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